

## SKILLS

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<b>Programming</b>	C++/C, Java, Python, Assembly (8051)
<b>Software</b>	Git, Gitlab, CMake, Linux, Qt Framework, QEMU, MATLAB, Jira, Polarion, Confluence
<b>Embedded</b>	Arduino, ESP32, ESP8266, Raspberry Pi Pico

## WORK EXPERIENCE

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<b>CNH Industrial</b>	Oak Brook, IL
<b>Embedded Software Engineer II – Guidance Team</b>	July 2024 - Present

- Worked on the guidance backend component in C++, processing operator inputs and real-time data for UI visualization in a Qt application, running on an embedded Linux device using Yocto.
- Led the development of agricultural swath recording features in C++, improving swath creation, selection, and deletion efficiency by 30% through event-driven workflows using Qt signals and slots.
- Accomplished real-time guidance line tracking for the first time on the new proprietary OS by developing swath rendering code, interfacing the swath generation output API with the display API.
- Improved operator setup and load times by 20% by offloading persistence operations to a separate thread, ensuring critical events are handled and displayed to the UI without delay.

<b>Embedded Software Engineer I – Automatic End-of-Row Turn (AEORT) Project</b>	July 2022 - July 2024
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- Led the development of an automated field turn planner that generates the shortest, drivable turns between swaths, by implementing a Dubins-Clothoid-based turning algorithm.
- Designed and proposed a dynamic turn planning solution to address collision turns, dividing them into sub-turns for re-planning, resulting in a formal IP submission.
- Accelerated the transition from proof-of-concept to production by leveraging existing interfaces, enabling rapid algorithm testing on agricultural vehicles via sideloading.
- Documented newly designed software at different levels using Doxygen, Markdown, Mermaid diagrams, ADRs, and Confluence, improving clarity throughout the development process.

## PROJECTS

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**GitHub Portfolio Page:** <https://daviycheng.github.io/>

### **Wearable Posture Corrector Device, Self-Project**

- Prototyped and designed a wearable posture-correction device using the SEFR machine learning algorithm to detect and notify users of prolonged slouching.
- Interfaced an accelerometer with a microcontroller over I2C for real-time posture monitoring.
- Extended battery life to 4.5 days by decreasing the system clock frequency and removing unused internal LEDs on the microcontroller.
- **Utilized:** C/C++, Python, Arduino, ATmega328 MCU, Multimeter, Soldering, Fusion 360

## EDUCATION

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<b>New York Institute of Technology</b>	Sept 2017 - May 2022
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<b>M.S. Electrical &amp; Computer Engineering</b>	GPA: 3.96/4.00
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<b>B.S. Electrical &amp; Computer Engineering</b>	GPA: 3.89/4.00
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Degree Honors: *summa cum laude*, Presidential Honor List (2018-2021)